

KEY

Exam 2
MATH 221-2

April 1, 2015

Chapters 1-5

100

1. (19 pts, 1 pt each) Circle T or F indicating whether each of the following statements are True or False. You do not need to justify your answers.

- (a) ~~T~~ F A 3 dimensional vector space must contain the 3×1 zero vector $\mathbf{0}$.
 (b) ~~T~~ F The set of vectors $[b_1 \ b_2 \ b_3]$ in \mathbb{R}^3 with $b_1 = b_2$ is a vector space.
 (c) T ~~F~~ If A is a randomly generated 10×13 matrix, then it is almost certain that A has 13 pivots.

- (d) ~~T~~ F If $\mathbf{x} \in N(A)$, then $A\mathbf{x} = \mathbf{0}$.

- (e) ~~T~~ F The rank of a matrix is the number of columns minus the number of free variables. (n)

- (f) T ~~F~~ The subspace of \mathbb{R}^2 spanned by all vectors with positive components is the positive quadrant of \mathbb{R}^2 . A $\mathbb{R}^n \rightarrow \mathbb{R}^m$

- (g) ~~T~~ F The vector \mathbf{c} is in $C(A^T)$ if $A^T \mathbf{y} = \mathbf{c}$ has a solution.

- (h) ~~T~~ F If $A\mathbf{x} = \mathbf{b}$ has a solution and if $A^T \mathbf{y} = \mathbf{0}$, then $\mathbf{b} \cdot \mathbf{y} = 0$.

- (i) ~~T~~ F For any matrix A , $C(A)$ and $N(A^T)$ are orthogonal vector spaces.

- (j) ~~T~~ F If \mathbf{x} and \mathbf{y} are orthogonal, then $\mathbf{x} \cdot \mathbf{y} = 1$.

- (k) T ~~F~~ If $A = \begin{bmatrix} | & | & & | \\ v_1 & v_2 & \dots & v_n \\ | & | & & | \end{bmatrix}$ then $\{v_1, v_2, \dots, v_n\}$ is a basis for $C(A)$.

- (l) T ~~F~~ If A is a 15×14 matrix then A^{-1} is a 14×15 matrix.

- (m) ~~T~~ F If A is a 3×3 matrix and $\dim(C(A)) = 3$ then A is invertible.

- (n) ~~T~~ F If the columns of A are linearly independent, then there is only one least squares solution to $A\mathbf{x} = \mathbf{b}$.

- (o) ~~T~~ F If $A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ -1 & 1 & -1 \end{bmatrix}$ then $\dim(C(A)) = 2$.

- (p) ~~T~~ F Any set of n linearly independent vectors in \mathbb{R}^n is a basis for \mathbb{R}^n .

- (q) ~~T~~ F If the columns of A are linearly independent, then there is always at least 1 solution to $A\mathbf{x} = \mathbf{b}$.

- (r) ~~T~~ F If A is a 3×2 matrix and $A\mathbf{x} = \begin{bmatrix} 5 \\ 1 \\ 3 \end{bmatrix}$ has only one solution then $N(A) = \{\mathbf{0}\}$.

2. (12 pts) Let $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix}$. Find the least squares solution to $Ax = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$. SHOW YOUR WORK!

$$A^T A \underline{x} = A^T \underline{b} \iff \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$$

$$\iff \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

$$\Rightarrow \boxed{\begin{matrix} x = 3 \\ y = 1 \end{matrix}}$$

3. (a) (8 pts) Let $A = \begin{bmatrix} 1 & 2 & 3 & 7 \\ 1 & 2 & 3 & -1 \\ 0 & 0 & 0 & 1 \\ 1 & 2 & 3 & 91 \end{bmatrix}$. Show that A is not invertible (using whatever method of your choice). Show your work.

Applying Gauss-Elimination: $R_2 \leftarrow -R_1 + R_2$
 $R_4 \leftarrow -R_1 + R_4$

$$\rightarrow \begin{bmatrix} 1 & 2 & 3 & 7 \\ 0 & 0 & 0 & -8 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 84 \end{bmatrix} \text{ shows that there are only}$$

2 pivots $\Rightarrow A$ is not invertible!!

- (b) (6 pts) Based on your answer to (a), for any RHS $b \in C(A)$, how many solutions do you expect to $Ax = b$? Explain.

Because A is not invertible, then $\dim(C(A)) = \dim(R(A))$ is less than 4 $\Rightarrow A$ has null spaces $N(A)$ and $N(A^T)$
 \Rightarrow By Fredholm Alternative, there are either 0 or ∞ of solutions for any RHS.

4. Let $A = \begin{pmatrix} 1 & 3 & 1 \\ 2 & 6 & 6 \end{pmatrix}$.

(a) (13 pts) Solve the system of linear equations

$$\begin{aligned} x + 3y + z &= 1 \\ 2x + 6y + 6z &= 10 \end{aligned}$$

Write the complete solution as a particular plus a null (or homogeneous) solution. SHOW YOUR WORK.

The augmented matrix is $\begin{bmatrix} 1 & 3 & 1 & 1 \\ 2 & 6 & 6 & 10 \end{bmatrix}$

Applying Gauss Elimination: $R_2 \leftarrow -2R_1 + R_2$, get:

$$\begin{bmatrix} 1 & 3 & 1 & 1 \\ 0 & 0 & 4 & 8 \end{bmatrix}. \text{ thus } 4z = 8 \Rightarrow \boxed{z = 2}.$$

Let y be free. So $x = 1 - 3y - z$
 $\boxed{x = -1 - 3y}$

$$\therefore \underline{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{bmatrix} -1 - 3y \\ y \\ 2 \end{bmatrix} = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} + y \begin{pmatrix} -3 \\ 1 \\ 0 \end{pmatrix}$$

$\uparrow \quad \quad \quad \uparrow$
 $\underline{x}_p \quad \quad \quad \underline{x}_n$

(b) (6 pts) Based on the work you did in #4a, give a basis for $C(A)$. Justify your answer.

ref(A) has pivots in columns 1 & 3.

$$\therefore C(A) = \text{span} \left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 6 \end{bmatrix} \right).$$

(c) (6 pts) Based on your answer to #4a, give a basis for $N(A)$. Justify your answer.

The basis for $N(A)$ is given by \underline{x}_n :

$$N(A) = \text{span} \left(\begin{bmatrix} -3 \\ 1 \\ 0 \end{bmatrix} \right).$$

- (d) (6 pts) Based on your answer to #4a, is $\begin{bmatrix} 1 \\ 10 \end{bmatrix} \in C(A)$? Explain why your answer is correct.

Yes, because we were able to solve

$$\underline{A} \underline{x} = \underline{b}.$$

- (e) (6 pts) For any non-zero $\underline{b} \in \mathbb{R}^2$ that one might choose, explain why finding only 1 solution to $\underline{A}\underline{x} = \underline{b}$ is impossible.

Because $N(A)$ is 1-dimensional
always generates an infinite # of
solutions via \underline{x}_n as in #4a.

- (f) (6 pts) For any $\underline{b} \in \mathbb{R}^2$ that one might choose, explain why finding no solutions to $\underline{A}\underline{x} = \underline{b}$ is impossible.

Because $C(A) = \mathbb{R}^2$ by #4b, all
RHS $\underline{b} \in \mathbb{R}^2$ have a solution to

$$\underline{A} \underline{x} = \underline{b}$$

5. (12 pts) For any $m \times n$ matrix A , prove that $N(A)$ is a vector space. Explicitly state the conditions that you are checking, and justify each step in your proof.

Closure wrt addition.

(A1) Let $\underline{u}, \underline{v} \in N(A)$. Is $\underline{u} + \underline{v} \in N(A)$?

$$\begin{aligned} \text{Consider: } A(\underline{u} + \underline{v}) &= A\underline{u} + A\underline{v} \quad \text{by distributive prop.} \\ &= \underline{0} + \underline{0} \quad \text{because } \underline{u}, \underline{v} \in N(A) \\ &= \underline{0}. \end{aligned}$$

$$\therefore \underline{u} + \underline{v} \in N(A).$$

(M1) Closure wrt scalar multiplication. Let $\underline{u} \in N(A)$. Is $\underline{c}\underline{u} \in N(A)$? any $c \in \mathbb{R}$

$$\begin{aligned} \text{Consider } A(c\underline{u}) &= c A\underline{u} \quad \text{by associativity} \\ &= c \underline{0} \quad \text{because } \underline{u} \in N(A). \\ &= \underline{0} \end{aligned}$$

$$\therefore c\underline{u} \in N(A).$$